

# Electro-optical Angle Transducers

Models DAB 58 - DAB 65 - DAB 66

## Calibrated analogue signal output

DAB 10465 CE

03 / 2003

- Minimum measuring range 0 to 90°
- Maximum measuring range 0 to 360°
- Contactless electro-optical sensor system
- With 12 Bit D/A-Converter
- Three different signal outputs at option:  
0 to 20 mA or 4 to 20 mA or 0 to 10 VDC
- Two adjustment modes to set measuring range, zero point and signal sense
- Robust, heavy duty design

### Construction

Flange and case in anodised aluminium - shaft in stainless steel - 12 mm ball-bearings with Nilos ring or radial packing ring seal - code disc in plastic or glass - GaAlAs diode and photo-transistor array - gate array - customer specific micro-processor - multifunctional ASIC - 12 Bit D/A converter - SMD technology.

The Models DAB 58, DAB 65 and DAB 66 have different shaft, flange and case dimensions and different types of electrical connections ( for details see page 3 ).



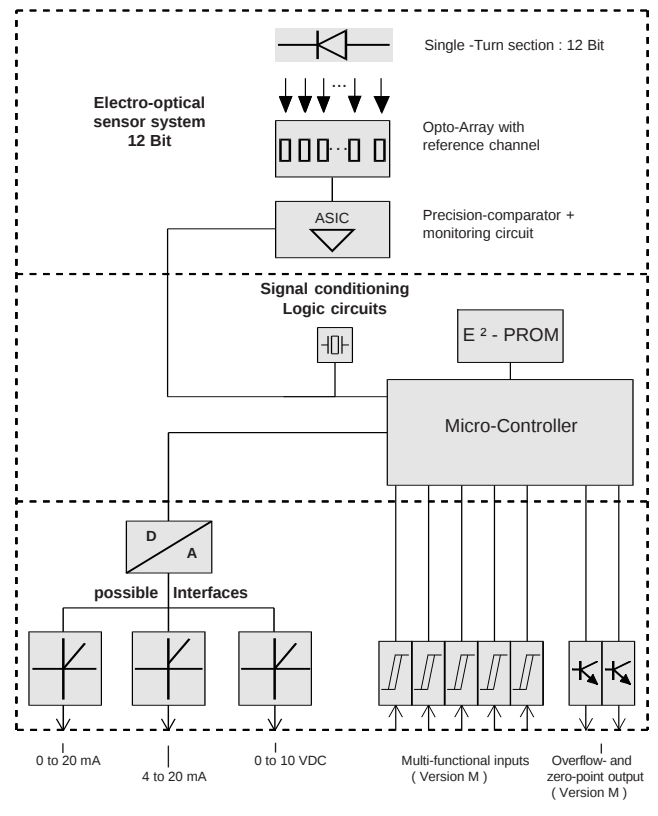
### Functional description and adjustment modes

The DAB Transducers have been derived from the CBE Single-turn-Encoders. They feature an electro-optical sensor system with digital signal processing and a D/A converter. The digital processing unit is designed to resolve any measuring range up to 360°. The 12 Bit D/A-converter transforms these positions into a proportional analogue signal.

If not otherwise specified the transducer will be supplied with a measuring range of 0 to 360° and CW signal sense, i.e. increasing output signal with view on shaft end. If the user chooses a smaller measuring range, e.g. 270°, there will be an overflow when leaving the specified range. In this event the output signal keeps its maximum level, i.e. 20 mA up to 360°. One of the two following adjustments modes must be specified on order :

- **Version „M“:** For remote control via five multi-functional inputs (MFP) at a 12-way connector. Two contacts are available to indicate zero-point and overflow.
- **Version „S“:** For adjustment in situ via two rotary switches which are located at the rear of the case. Two LED indicate zero point and overflow.

For further details refer to page 2.



### Technical Data

( Valid for both versions unless otherwise stated )

- Sensor system: GaAlAs diode, photo-transistor array, precision comparator
- Disc coding: Gray code
- Setting cycles EEPROM:  $\geq 10^6$
- Signal sense: CW or CCW (signal input E6)
- Supply voltage range  $V_s$ : + 20 to + 26 VDC  
15  $\pm$  0,5 VDC (optional)
- Supply current  $I_s$ : 70 mA typ. / 90 mA max.  
(when output current = 0)
- Linearity: 0.025% typ. / 0.05% max. ( $\pm$  2 LSB)  
12 Bit monotony warranted
- Temperature drift: 0.0015 % /K typ.

### Current output

- Accuracy
  - at starting point 0 mA: 0 mA  $\pm$  5  $\mu$ A typ /  $\pm$  15  $\mu$ A max.
  - 4 mA: 4 mA  $\pm$  5  $\mu$ A typ /  $\pm$  15  $\mu$ A max.
  - at end point 20 mA: 20 mA  $\pm$  5  $\mu$ A typ /  $\pm$  15  $\mu$ A max.
- Load resistance: 0 to 500  $\Omega$  at  $V_s$  = 20 to 26 VDC

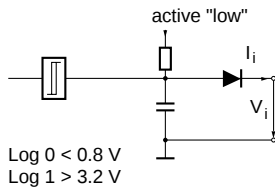
### Voltage output

- Accuracy
  - at starting point 0 V: 0 V  $\pm$  2.5 mV typ. /  $\pm$  7.5 mV max.
  - at end point 10 V: 10 V  $\pm$  2.5 mV typ. /  $\pm$  7.5 mV max.
- Output current: 5 mA max. When load resistance > 2k $\Omega$  (short circuit proof)

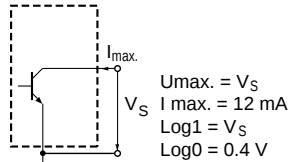
## Version "M"

- Multi functional inputs: Signal input E2
- Zero-point output: Open collector / output B
- Overflow output: Open collector / output B

### Signal input E2



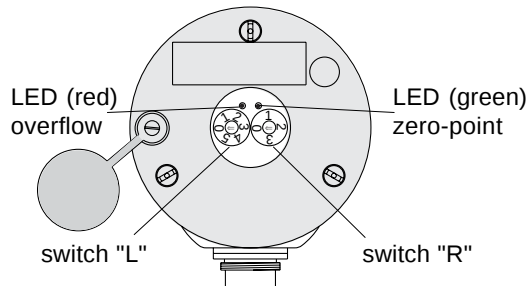
### Signal output B



## Version "S"

- 2 Rotary switches: 6 functions
- Zero-point signal: LED
- Overflow signal: LED

### Rear View of version "S"



## Electrical connections

- Version "M": Round connector 12-way, (IP65), radially on case
- Version "S": Round connector 4-way, (IP65), radially on case

## Mechanical Data

- Operating speed: 3000 rpm max. (continuous)  
4000 rpm max. (short period)
- Operating torque:  $\leq 5$  Ncm (8 Ncm - DAB 66)
- Wind-up torque:  $\leq 1$  Ncm (4 Ncm - DAB 66)
- Angular acceleration:  $10^5$  rad/s<sup>2</sup> max.
- Inertial mass of rotor: 50 gcm<sup>2</sup>
- Permissible axial and radial shaft load: 250 N max.
- Bearing life expectancy:  $10^9$  turns

## Environmental Data

- Operating temperature range: - 20°C to + 60°C
- Storage temperature range: - 25°C to + 70°C
- Permissible rel. humidity: 85% without condensation
- Resistance to shock: 200 m/s<sup>2</sup> ; 11 ms (DIN IEC 68)
- Resistance to vibration: 5 Hz ... 1000 Hz ; 100 m/s<sup>2</sup> (DIN IEC 68)
- Protection class (DIN 40050)
  - DAB 58, 65 and 105: IP 65 (Nilos ring)
  - DAB 66: IP 66 (radial packing ring)
- Mass: 0.5 kg

## Adjustment operations

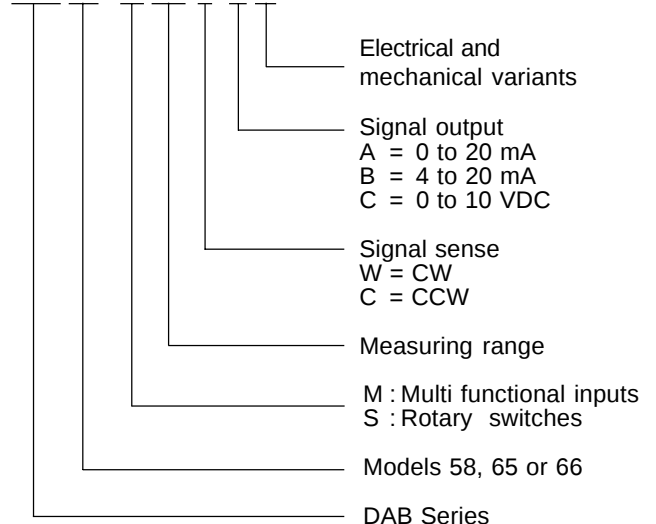
The following adjustment operations can be carried out in situ when the transducer is mounted and coupled to its driving device:

- **Measuring range**
  - Setting of zero-point at specified mechanical position
  - Setting of end-point at specified mechanical position
- **Adjustment of zero-point** without changing of specified measuring range
- **Adjustment of measuring range** without changing of specified zero-point
- **Signal sense** either CW or CCW
- **The basic output feature**, i.e. 360° measuring range and CW signal sense, can be reproduced whenever required.

For further details please refer to the operating instruction sheet which is supplied with each item.

## Order code format

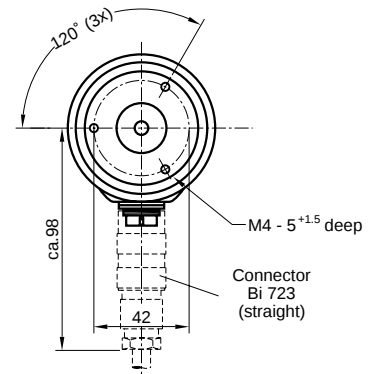
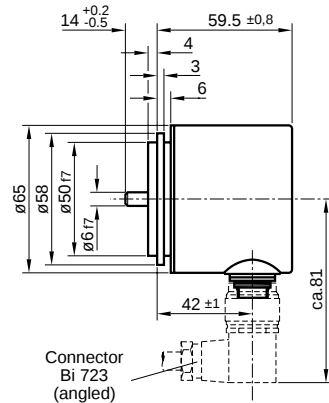
DAB 58 - M 360 W A 01



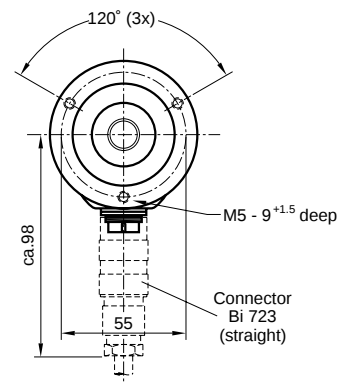
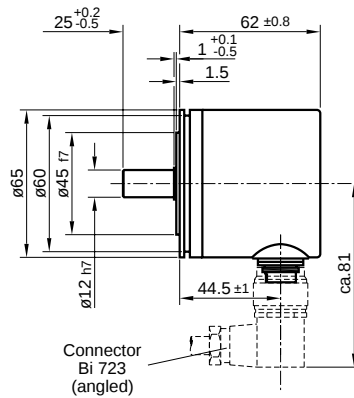
# Electro-optical Angle Transducer DAB 58, 65 and 66

## Dimensions in mm

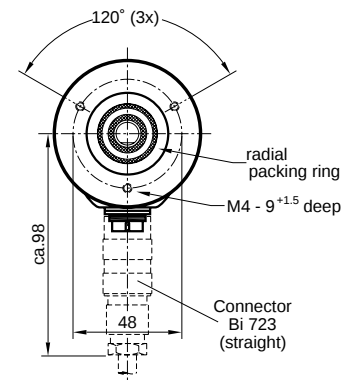
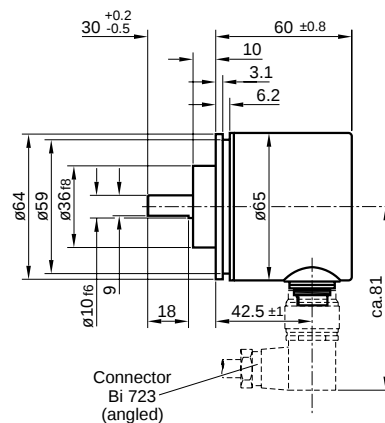
### Model DAB 58 with synchro-flange



### Model DAB 65 with synchro-flange



### Model DAB 66 with clamping flange, shaft with flat



**Accessories :** Straight connectors are included in the supplied items. Angled connectors are supplied on order. Couplings can be supplied as per Data Sheet KW 10112.

Version "M" : 12-way connector  
Version "S" : 4-way connector

# Electro - optical Angle Transducer DAB 58, 65 and 66

**Table of multi-functional inputs (mfp) for version "M"**

| Function                          |        | MFP4 | MFP3 | MFP2 | MFP1 | MFP0 |
|-----------------------------------|--------|------|------|------|------|------|
| Adjustment of standard values     |        | 0    | 1    | 0    | 1    | 0    |
|                                   |        | 0    | 1    | 0    | 0    | X    |
| Adjustment of output signal sense | (CW)   | 0    | 1    | 1    | 1    | 0    |
|                                   | (CCW)  | 0    | 1    | 1    | 0    | X    |
| Adjustment of measuring range:    |        |      |      |      |      |      |
| - by zero point adjustment to     | (zero) | 1    | 0    | 0    | 1    | 0    |
| - by adjustment of range to       | (max.) | 1    | 0    | 0    | 0    | X    |
| Zero point adjustment:            |        |      |      |      |      |      |
| - increase output value           |        | 1    | 0    | 1    | 1    | 0    |
| - decrease output value           |        | 1    | 0    | 1    | 0    | X    |
| Changing of measuring:            |        |      |      |      |      |      |
| - increase range value            |        | 1    | 1    | 0    | 1    | 0    |
| - decrease range value            |        | 1    | 1    | 0    | 0    | X    |
| End of adjustment                 |        |      |      |      |      |      |
| Normal transducer function        |        | 1    | 1    | 1    | 1    | 1    |

CW = Increasing output signal when turning the shaft clockwise

CCW = Increasing output signal when turning the shaft counter - clockwise

## Timing diagrams

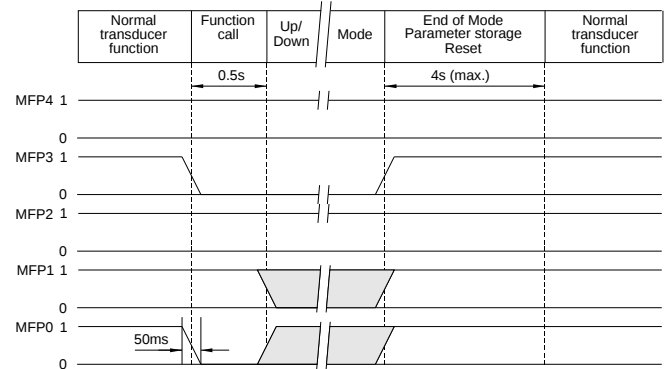
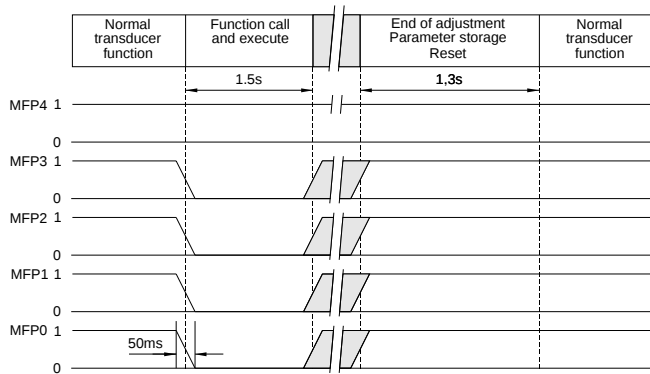
Adjustment of measuring range

Adjustment of standard values

Adjustment of output signal sense

Zero point adjustment

Changing of measuring



**Table of switch functions for version "S"**

| Function                          |        | switch L | switch R |
|-----------------------------------|--------|----------|----------|
| Adjustment of standard values     |        | 5        | 1        |
| Adjustment of output signal sense | (CW)   | 4        | 1        |
|                                   | (CCW)  | 4        | 3        |
| Adjustment of measuring range:    |        |          |          |
| - by zero point adjustment to     | (zero) | 3        | 1        |
| - by adjustment of range to       | (max.) | 3        | 3        |
| Zero point adjustment:            |        |          |          |
| - increase output value           |        | 2        | 1        |
| - decrease output value           |        | 2        | 3        |
| Changing of measuring:            |        |          |          |
| - increase range value            |        | 1        | 1        |
| - decrease range value            |        | 1        | 3        |
| End of adjustment                 |        |          |          |
| Normal transducer function        |        | 0        | 0        |

First select function by switch L then execute function by switch R.

After execution use switch R before switch L to select function "end of adjustment".